

motor controller

CMMP-AS-C10-11A-P3-M3

Part number: 1501328

FESTO

One plug-in module CAMC-DS-M1, CAMC-G-S1 or CAMC-G-S3 is required in order to operate the motor controller CMMP-AS-...-M3.



Data sheet

Feature	Value
Mounting type	On sub-base Tightened
Product weight	3,450 g
Display	Seven-segment display
Authorisation	RCM Mark c UL us - Listed (OL)
CE mark (see declaration of conformity)	to EU directive for EMC to EU directive for machinery to EU directive low-voltage devices
Storage temperature	-25 ... 70 °C
Ambient temperature	0 ... 40 °C
Relative air humidity	0 - 90 %
Protection class	IP10 IP20
Degree of contamination	2
Materials note	Contains PWIS substances Conforms to RoHS
Nominal operating voltage, phases	Three-phase
Nominal operating voltage, AC	400 V
Permissible voltage fluctuation	+/- 10 %
Line frequency	50 ... 60 Hz
Nominal current	11 A
Mains filter	Integrated
Max. intermediate circuit voltage, DC	560 V
Braking resistance	68 Ohm
Braking resistance pulse power	8.5 kVA
Nominal DC voltage, logic power supply	24 V
Permissible range, logic voltage	± 20 %
Current consumption, logic power supply without clamping brake	1 A
Output voltage range AC	3x 0 - 360 V
Nominal output current	10 A
Effective nominal current per phase	10 A
Effective peak current per phase	20 A
Max. peak current duration	5 s
Nominal controller power	6,000 VA
Peak power	12,000 VA
Output frequency	0 ... 1,000 Hz
Parameters configuring interface	Parameters configuration and commissioning USB Ethernet
Fieldbus coupling	CANopen DeviceNet EtherCAT

Feature	Value
	EtherNet/IP Modbus/TCP PROFINET Profibus DP
Communications profile	DS301/DSP402 FHPP
Process interface	I/O coupling For 256 position sets
Max. fieldbus transmission speed	1 Mbit/s
Bus connection	Plug 9-pin Sub-D
Encoder interface output, characteristics	Resolution 16384 ppr
Encoder interface output, function	Actual value feedback via encoder signals in speed control mode Setpoint specification for downstream slave drive unit
Encoder interface input, characteristics	3-phase encoding signals EnDat HIPERFACE RS422 SINCOS
Encoder interface input, function	Encoder signal, speed setpoint in RPM In synchronous operation as specified speed in RPM for the slave drive unit
Number of digital logic inputs	10
Logic input characteristics	Electrically isolated Freely configurable
Logic input working range	8 ... 30 V
Number of 24 V DC digital logic outputs	5
Digital logic output characteristics	Electrically isolated Freely configurable to a given extent
Max. current, digital logic outputs	100 mA
Number of analogue setpoint inputs	2
Setpoint input characteristics	Differential inputs Can be configured for speed in RPM Can be configured for current
Setpoint input working range	± 10 V
Setpoint input impedance	20 kOhm
Number of analogue monitor outputs	2
Monitor output working range	± 10 V
Monitor output resolution	9 Bit
Monitor output characteristics	Short-circuit proof